# Recent Results on Generalized Baumslag-Solitar Groups

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## Baumslag-Solitar groups

(i) A Baumslag-Solitar group is a group with a presentation

$$BS(m, n) = \langle t, x \mid (x^m)^t = x^n \rangle,$$

where  $m, n \in \mathbb{Z}^* = \mathbb{Z} \setminus \{0\}$ .

(ii) A similar type of 1-relator group is

$$K(m,n) = \langle x,y \mid x^m = y^n \rangle,$$

where  $m, n \in \mathbb{Z}^*$ .

These are the fundamental groups of certain graphs of groups.

## **GBS-graphs**

Let  $\Gamma$  be a finite connected graph. For each edge e label the endpoints  $e^+$  and  $e^-$ . Infinite cyclic groups  $\langle g_x \rangle$  and  $\langle u_e \rangle$  are assigned to each vertex x and edge e.

Injective homomorphisms  $\langle u_e \rangle o \langle g_{e^+} \rangle$  and  $\langle u_e \rangle o \langle g_{e^-} \rangle$  are defined by

$$u_e \mapsto g_{e^+}^{\omega^+(e)} \text{ and } u_e \mapsto g_{e^-}^{\omega^-(e)}$$

where  $\omega^+(e), \ \omega^-(e) \in \mathbb{Z}^*$ .

## **GBS-graphs**

So we have a weight function

$$\omega: E(\Gamma) \to \mathbb{Z}^* \times \mathbb{Z}^*$$

where  $\omega(e)=(\omega^-(e),\omega^+(e))$  is defined up to  $\pm$ . The weighted graph

$$(\Gamma, \omega)$$

is a generalized Baumslag-Solitar graph or GBS-graph.

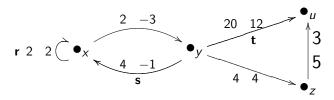
## **GBS**-groups

The generalized Baumslag-Solitar group (GBS-group) determined by the GBS-graph  $(\Gamma, \omega)$  is the fundamental group  $G = \pi_1(\Gamma, \omega)$ . If T is a maximal subtree of  $\Gamma$ , then G has generators  $g_x$  and  $t_e$ , with relations

$$\begin{cases} g_{e^+}^{\omega^+(e)} &= g_{e^-}^{\omega^-(e)}, \text{ for } e \in E(T), \\ (g_{e^+}^{\omega^+(e)})^{t_e} &= g_{e^-}^{\omega^-(e)}, \text{ for } e \in E(\Gamma) \backslash E(T). \end{cases}$$

If  $\Gamma$  is an edge e, G=K(m,n): if  $\Gamma$  is a single loop e, G=BS(m,n), where  $m=\omega^+(e), n=\omega^-(e)$ .

#### An example



The maximal subtree T is the path x, y, z, u. The GBS-group has a presentation in  $r, s, t, g_x, g_y, g_z, g_u$  with relations

$$g_x^2 = g_y^{-3}, \ g_y^4 = g_z^4, \ g_z^5 = g_u^3$$
  
 $(g_x^2)^r = g_x^2, \ (g_x^4)^s = g_y^{-1}, \ (g_u^{12})^t = g_y^{20}.$ 

## Some properties of GBS-groups

Let  $G = \pi_1(\Gamma, \omega)$  be a GBS-group.

- (i) G is independent of the choice of maximal subtree.
- (ii) G is finitely presented and torsion-free.
- (iii) If  $\Gamma$  is a tree, then G is residually finite and hence is hopfian.

The next result is due to P. Kropholler.

(iv) The non-cyclic GBS-groups are exactly the finitely generated groups of cohomological dimension 2 which have a commensurable infinite cyclic subgroup.

## Some properties of GBS-groups

(v) If H is a finitely generated subgroup of a GBS-group G, either H is a GBS-group or it is free. Hence G is coherent.

*Proof.* We have  $cd(H) \le cd(G) = 2$ . If cd(H) = 1, then H is free by the Stallings-Swan Theorem. Otherwise cd(H) = 2. If H contains a commensurable element, it is a GBS-group by (iv). If H has no commensurable elements, it is free.

(vi) The second derived subgroup of a GBS-group is free. (Kropholler.)

## The weight of a path

Let  $(\Gamma, \omega)$  be a *GBS*-graph with a maximal subtree T. Let  $e = \langle x, y \rangle$  be a non-tree edge where  $x \neq y$ . There is a unique path in T from x to y, say

$$x = x_0, x_1, \ldots, x_n = y.$$

Then there is a relation in  $G = \pi_1(\Gamma, \omega)$ 

$$g_x^{p_1(e)} = g_y^{p_2(e)}$$

where  $p_1(e)$  and  $p_2(e)$  are the products of the left and right weight values of the edges in the tree path [x, y].

## The weight of a path

**Lemma 1.** Let  $(\Gamma, \omega)$  be a GBS-graph with a maximal subtree T. Let  $\alpha = [x, y]$  be a path in T. Then there exist  $a, b \in \mathbb{Z}^*$  such that  $g_x^a = g_y^b$  in  $\pi_1(\Gamma, \omega)$ . Also, if  $g_x^m = g_y^n$ , then (m, n) = (a, b)q for some  $q \in \mathbb{Z}^*$ .

**Definition.** Call (a, b) the weight of the path  $\alpha$  in T and denote it by  $\omega_T(\alpha)$  or

$$\omega_T(x,y) = (\omega_T^{(1)}(x,y), \omega_T^{(2)}(x,y)).$$

This is unique up to  $\pm$ .

## How to compute the weight of a path

Let  $\alpha$  be the path  $x=x_0,x_1,\ldots,x_n=y$  and write  $\omega(\langle x_i,x_{i+1}\rangle)=(u_i^{(1)},\ u_i^{(2)}),\ i=0,1,\ldots,n-1.$  Define  $(\ell_i,m_i),\ 0\leq i\leq n,$  recursively by  $\ell_0=1=m_0$  and

$$\ell_{i+1} = \frac{\ell_i u_i^{(1)}}{\gcd(m_i, u_i^{(1)})}, \quad m_{i+1} = \frac{m_i u_i^{(2)}}{\gcd(m_i, u_i^{(1)})}.$$

Then

**Lemma 2.**  $\omega_T(x, y) = (\ell_n, m_n)$ .

## Tree and skew tree dependence

Let  $(\Gamma, \omega)$  be a GBS-graph with a maximal subtree T. The non-tree edge  $e = \langle x, y \rangle$  is called T-dependent or skew T-dependent if and only if

$$\frac{\omega^{-}(e)}{\omega^{+}(e)} = \frac{\omega_{T}^{(1)}(e)}{\omega_{T}^{(2)}(e)} \text{ or } -\frac{\omega_{T}^{(1)}(e)}{\omega_{T}^{(2)}(e)}$$

respectively. If e is a loop, then e is T-dependent (skew T-dependent) if and only if  $\omega^-(e) = \omega^+(e)$  or  $\omega^-(e) = -\omega^+(e)$  respectively.

#### Tree and skew tree dependence

If every non-tree edge of a GBS-graph is T-dependent, the GBS-graph is called  $tree\ dependent$ .

If every non-tree edge is T-dependent or skew T-dependent with at least of the latter, then the GBS-graph is called *skew tree dependent*.

These properties are independent of the choice of T.

Tree dependence is relevant to the computation of homology in low dimensions.

# Homology in dimensions $\leq 2$

**Theorem 1.** (DR). Let  $G = \pi_1(\Gamma, \omega)$  be a GBS-group. Then the torsion-free rank of  $H_1(G) = G_{ab}$  is

$$r_0(G) = |E(\Gamma)| - |V(\Gamma)| + 1 + \epsilon$$

where  $\epsilon = 1$  if  $(\Gamma, \omega)$  is tree dependent and otherwise  $\epsilon = 0$ . Hence tree dependence is independent of the choice of maximal subtree.

**Theorem 2.** (DR). For any GBS-group G the Schur multiplier  $H_2(G)$  is free abelian of rank  $r_0(G) - 1$ .

#### The $\Delta$ -function

Let G be a group with a commensurable element x of infinite order. If  $g \in G$ , then  $\langle x \rangle \cap \langle x \rangle^g \neq 1$  and  $(x^n)^g = x^m$  for  $m, n \in \mathbb{Z}^*$ . Define  $\Delta_x(g) = \frac{m}{n}$ . Then

$$\Delta_{x}: G \mapsto \mathbb{Q}^{*}$$

is a well defined homomorphism.

If  $y \in G$  is commensurable and  $\langle x \rangle \cap \langle y \rangle \neq 1$ , then  $\Delta_x = \Delta_y$ . If this holds for all commensurable elements, then  $\Delta_x$  depends only on G: denote it by

$$\Delta^G$$
.

## The $\Delta$ -function of a GBS-group

A GBS-graph  $(\Gamma, \omega)$  or the group  $G = \pi_1(\Gamma, \omega)$ , is called elementary if  $G \simeq BS(1, \pm 1)$ . If G is non-elementary, then each commensurable element of G is elliptic and hence is conjugate to a power of some  $g_v$ . Hence  $\Delta^G$  is unique.

**Lemma 3.** Let  $(\Gamma, \omega)$  be a non-elementary GBS-graph, with T a maximal subtree, and let  $G = \pi_1(\Gamma, \omega)$ . Then:

(i) 
$$\Delta^{G}(g_{v}) = 1$$
 for all  $v \in V(\Gamma)$ ;

(ii) If 
$$e \in E(\Gamma) \backslash E(T)$$
,  $\omega(e) = (a, b)$ ,  $\omega_T(e) = (m, n)$ , 
$$\Delta^G(t_e) = \frac{an}{bm}.$$

## Unimodular groups

**Corollary.** (G. Levitt). Let e be a non-tree edge. Then:

- (i) e is T-dependent if and only if  $\Delta^G(t_e) = 1$ . Hence  $(\Gamma, \omega)$  is tree dependent if and only if  $\Delta^G$  is trivial.
- (ii) e is skew T-dependent if and only if  $\Delta^G(t_e) = -1$ . Hence  $(\Gamma, \omega)$  is skew tree dependent if and only if  $\operatorname{Im}(\Delta^G) = \{\pm 1\}$ .

If  $\operatorname{Im}(\Delta^G) \subseteq \{\pm 1\}$ , call  $G = \pi_1(\Gamma, \omega)$  unimodular.

## The centre of a GBS-group

The following result tells us when the center of a GBS-group is non-trivial.

**Theorem 3.** Let  $(\Gamma, \omega)$  be a GBS-graph and let G be its fundamental group. Assume that G is non-elementary. Then the following are equivalent.

- (a) Z(G) is non-trivial.
- (b)  $\Delta^G$  is trivial.
- (c)  $(\Gamma, \omega)$  is tree-dependent.

#### Locating the centre

Let  $(\Gamma, \omega)$  be a GBS-graph. In finding Z(G) we may assume the graph is non-elementary. We can also assume  $(\Gamma, \omega)$  is tree dependent since otherwise Z(G) = 1.

In a GBS-graph the distal weight of a leaf in a maximal subtree is the weight occurring at the vertex of degree 1. In finding the centre there is no loss in assuming there are no leaves with distal weight  $\pm 1$ .

#### Locating the centre

**Lemma 4.** Let  $(\Gamma, \omega)$  be a non-elementary GBS-graph with a maximal subtree T. Assume no leaves of T have distal weight  $\pm 1$ . Then

$$Z(G) \leq \bigcap_{x \in V(\Gamma)} \langle g_x \rangle.$$

For any  $x, v \in V(\Gamma)$ ,  $\langle g_x \rangle \cap \langle g_v \rangle = \langle g_v^{\omega_T^{(1)}(v,x)} \rangle$ . Hence  $\bigcap_{x \in V(\Gamma)} \langle g_x \rangle = \langle g_v^{h_v} \rangle$  where

$$h_{\mathbf{v}} = \operatorname{lcm}\{\omega_{T}^{(1)}(\mathbf{v}, \mathbf{x}) \mid \mathbf{x} \in V(\Gamma)\} = \omega_{T}^{tot}(\mathbf{v}),$$

the total weight of v in T.

#### Locating the centre

The total weight of v in T is the smallest positive power of  $g_v$  belonging to every vertex subgroup.

There is a more economic expression for the total weight. Let  $y_1, y_2, \ldots, y_k$  be the vertices of degree 1 in T. Then

$$\omega_T^{tot}(\mathbf{v}) = \operatorname{lcm}\{\omega_T^{(1)}(\mathbf{v}, \mathbf{y}_i) \mid i = 1, 2, \dots, m\}.$$

## How to compute the centre of a GBS-group

**Lemma 5.** Let  $(\Gamma, \omega)$  be a non-elementary GBS-graph with maximal subtree T. Assume that no leaf in T has distal weight  $\pm 1$ . Then

$$Z(G) = \bigcap_{e \in E(\Gamma) \setminus E(T)} C_J(t_e),$$

where  $J = \bigcap_{x \in V(\Gamma)} \langle g_x \rangle$ . If  $\Gamma = T$ , then Z(G) = J.

The centralizers in this formula can be found using:

**Lemma 6.** Let  $e = \langle x, y \rangle \in E(\Gamma) \backslash E(T)$  be T-dependent and let  $\omega(e) = (m, n)$  and  $\omega_T(x, y) = (a, b)$ . Then  $C_{\langle g_x \rangle}(t_e) = \langle g_x^{\operatorname{lcm}(a, m)} \rangle$ .

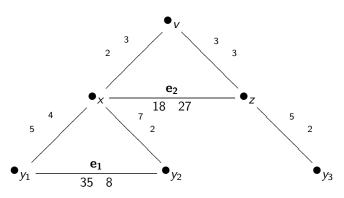
## A formula for the centre of a GBS-group

**Theorem 4.** (A. Delgado, DR, M. Timm.) Let  $(\Gamma, \omega)$  be a non-elementary, tree dependent GBS-graph with a maximal subtree T. Assume no leaf in T has distal weight  $\pm 1$ . Let v be any fixed vertex and let the non-tree edges be  $e_i = \langle x_i, y_i \rangle$ ,  $i = 1, 2, \ldots, k$ . Put  $\omega(e_i) = (m_i, n_i)$ ,  $\omega_T(x_i, y_i) = (a_i, b_i)$ ,  $\omega_T(v, x_i) = (c_i, d_i)$ , and  $\ell_i = \operatorname{lcm}(a_i, m_i)$ . Then  $Z(G) = \langle g_v^{f_v} \rangle$  where

$$f_{v} = \operatorname{lcm}\left\{\frac{c_{i}\ell_{i}}{\gcd(\ell_{i},d_{i})}, \ \omega_{T}^{tot}(v) \mid i=1,2,\ldots,k\right\}.$$

Call  $f_v = \omega_{\Gamma}^{tot}(v)$ , the total weight of v in  $(\Gamma, \omega)$ .

#### An example



The two non-tree edges are  $e_1, e_2$  and v is the root of the maximal subtree T, while  $y_1, y_2, y_3$  are the vertices of degree 1 in T. The edges  $e_1$  and  $e_2$  are T-dependent, so  $(\Gamma, \omega)$  is tree dependent and  $Z(G) \neq 1$ .

## An example

Read off the required data from the GBS-graph.

$$\omega_T^{tot}(v) = \text{lcm}(\omega_T^{(1)}(v, y_1), \omega_T^{(1)}(v, y_2), \ \omega_T^{(1)}(v, y_3)) = 210.$$

Next

$$(m_1, n_1) = \omega(e_1) = (35, 8), \ (m_2, n_2) = \omega(e_2) = (18, 27), \ (a_1, b_1) = \omega_T(y_1, y_2) = (35, 8), \ (a_2, b_2) = \omega_T(x, z) = \ (2, 3), \ (c_1, d_1) = \omega_T(v, y_1) = (6, 5), \ (c_2, d_2) = \ \omega_T(v, x) = (3, 2).$$

Hence  $\ell_1=35, \ell_2=18$  and  $\omega_{\Gamma}^{tot}(v)=1890$ . Therefore  $Z(G)=\langle g_v^{1890}\rangle$ .

## Cyclic normal subgroups in GBS-groups

In skew tree dependent GBS-graphs the role of the centre is played by the unique maximum normal cyclic subgroup.

**Lemma 7.** Let  $(\Gamma, \omega)$  be a non-elementary GBS-graph. Then  $G = \pi_1(\Gamma, \omega)$  has a unique maximal cyclic normal subgroup C(G).

*Proof.* Suppose  $\{C_i|i\in I\}$  is an infinite ascending chain of cyclic normal subgroups of G. Each  $C_i$  is commensurable and hence lies in a vertex subgroup. Hence infinitely many of the  $C_i$  lie in some  $\langle g_v \rangle$ , a contradiction. Hence G has a maximal cyclic normal subgroup C.

## Cyclic normal subgroups in GBS-groups

It is straightforward to show *C* is unique.

**Corollary.**  $C(G) \leq \bigcap_{v \in V(\Gamma)} \langle g_v \rangle = J$  and hence

$$C(G) = \bigcap_{e \in E(\Gamma) \setminus E(T)} J_{\langle t_e \rangle},$$

where  $J_{\langle t_e \rangle}$  is the  $\langle t_e \rangle$ -core of J.

The subgroup C(G) in a GBS-group can be trivial.

## Cyclic normal subgroups in GBS-groups

**Lemma 8.** Let  $G = \pi_1(\Gamma, \omega)$  be a non-elementary GBS-group. Then:

(i)  $C(G) \neq 1$  if and only if  $\pi_1(\Gamma, \omega)$  is unimodular, i.e.,  $(\Gamma, \omega)$  is either tree dependent or skew-tree dependent.

(ii) 1 = Z(G) < C(G) if and only if  $(\Gamma, \omega)$  is skew tree dependent.

# Computing C(G)

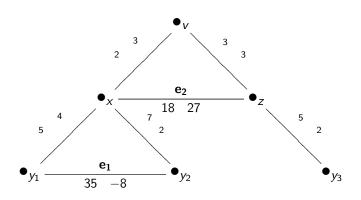
The algorithm to compute the centre of a tree dependent GBS-graph can be applied to a skew tree dependent GBS-graph  $(\Gamma, \omega)$ , with cores playing the role of centralizers. It will then compute  $C(\pi_1(\Gamma, \omega))$ .

**Theorem 5.** (A.Delgado, DR, M.Timm.) Let  $(\Gamma, \omega)$  be a non-elementary, skew tree dependent GBS-graph with a maximal subtree T having no distal weights  $\pm 1$ . Then if  $G = \pi_1(\Gamma, \omega)$  and v is any vertex v,

$$C(G) = \langle g_v^{\omega_\Gamma^{tot}(v)} \rangle.$$

#### An example

Change the weight of edge  $e_1$  in the last example from (35, 8) to (35, -8).



$$Z(G) = 1, \quad C(G) = \langle g_{\nu}^{\omega_{\Gamma}^{tot}(\nu)} \rangle = \langle g_{\nu}^{1890} \rangle.$$

## GBS-groups and 3-manifold groups

What is the relation between GBS-groups and 3-manifold groups, i.e., the fundamental groups of compact 3-manifolds?

# Some examples (W. Heil).

- **1.**  $K(m, n) = \langle x, y \mid x^m = y^n \rangle$  is a 3-manifold group.
- $\bullet_X \xrightarrow{m} {n } \bullet_y$
- **2.** The group  $\langle x_1, x_2, x_3 \mid x_1^m = x_2^n, x_2^m = x_3^n \rangle$  is a 3-manifold group iff |m| = 1 or |n| = 1 or |m| = |n|.
- $\bullet_{x_1} \, \underline{\hskip 1cm m \hskip 1cm \hskip 1cm n} \, \bullet_{x_2} \, \underline{\hskip 1cm m \hskip 1cm \hskip 1cm n} \, \bullet_{x_3}$

## GBS-groups and 3-manifold groups

**3.**  $B(m, n) = \langle t, x \mid x^n = (x^m)^t \text{ is a 3-manifold group iff } | m | = |n|.$ 

*Problem.* Find necessary and sufficient conditions on a GBS-graph  $(\Gamma, \omega)$  for  $\pi_1(\Gamma, \omega)$  to be the fundamental group of a compact 3-manifold.

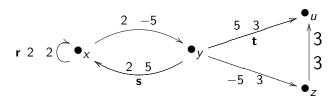
A GBS-graph  $(\Gamma, \omega)$  is called *locally weight constant* if at every vertex v all weights equal  $c_v$  and *locally*  $\pm$  *weight constant* if all weights at v equal  $\pm c_v$  for some constant  $c_v$ .

## Locally $\pm$ weight constant GBS-graphs

#### Remarks

Let  $(\Gamma, \omega)$  be a GBS-graph. If  $(\Gamma, \omega)$  is locally weight constant GBS-graph, it is tree dependent. If it is locally  $\pm$  weight constant, it is tree or skew tree dependent, i.e., it is unimodular.

**Example** The GBS-graph shown is locally  $\pm$  weight constant, but not locally weight constant.



## The GBS-groups which are 3-manifold groups

**Theorem 6.** (A. Delgado, DR, M.Timm.) Let  $(\Gamma, \omega)$  be a non-elementary GBS-graph. Then the following are equivalent.

- (i)  $\pi_1(\Gamma, \omega)$  is a 3-manifold group.
- (ii)  $\pi_1(\Gamma, \omega)$  is an orientable 3-manifold group.
- (iii)  $(\Gamma, \omega)$  is locally  $\pm$  weight constant.

This explains Heil's examples: B(m, n) is a 3-manifold group if and only if |m| = |n|.

## 3-manifold GBS-group covers

Let  $(\Gamma, \omega)$  be a non-elementary GBS-graph. If  $\pi_1(\Gamma, \omega)$  is not a 3-manifold group, it may be a quotient of a GBS-group which is a 3-manifold group.

A 3-manifold GBS-group cover of  $\pi_1(\Gamma, \omega)$  is a surjective homomorphism

$$\varphi: \pi_1(\Gamma, \tau) \to \pi_1(\Gamma, \omega)$$

where  $(\Gamma, \tau)$  is a GBS-graph such that  $\pi_1(\Gamma, \tau)$  is a 3-manifold group, and  $\varphi$  is a *pinch map*, which arises by dividing the weights on certain edges of  $\Gamma$  by common factors.

## The GBS-groups with 3-manifold GBS-group covers

**Theorem 7.** (A. Delgado, DR, M.Timm.) Let  $(\Gamma, \omega)$  be a non-elementary GBS-graph. Then the following are equivalent.

- (i)  $\pi_1(\Gamma, \omega)$  has a 3-manifold GBS-group cover.
- (ii)  $\pi_1(\Gamma, \omega)$  has an orientable 3-manifold GBS-group cover.
- (iii)  $\pi_1(\Gamma, \omega)$  is unimodular, i.e.,  $(\Gamma, \omega)$  is tree dependent or skew tree dependent.

## The total weight cover of a GBS-group

Suppose that  $(\Gamma, \omega)$  is a non-elementary GBS-graph such that  $\pi_1(\Gamma, \omega)$  unimodular. We show how to construct a 3-manifold GBS-group cover of  $\pi_1(\Gamma, \omega)$ .

**Case**:  $(\Gamma, \omega)$  is tree dependent.

Define a new weight function  $\tau$  on  $\Gamma$  as follows:

$$\tau(e) = (\omega_{\Gamma}^{tot}(e^{-}), \omega_{\Gamma}^{tot}(e^{+}), e \in E(\Gamma).$$

Call the GBS-graph  $(\Gamma, \tau)$  the *total weight cover* of  $(\Gamma, \omega)$ .

## Constructing 3-manifold GBS-group covers

Clearly the total weight cover is locally weight constant, so  $\pi_1(\Gamma, \tau)$  is a compact (orientable) 3-manifold group.

The identity map on  $\Gamma$  and a suitable sequence of pinches yields a surjective homomorphism

$$\varphi: \pi_1(\Gamma, \tau) \to \pi_1(\Gamma, \omega)$$

which is a 3-manifold GBS-group cover of  $\pi_1(\Gamma, \omega)$ .

## The total $\pm$ weight cover

**Case**:  $(\Gamma, \omega)$  is skew tree dependent

Let T be a maximal subtree in  $\Gamma$ . We can assume that all weights in T are positive. Write  $E(\Gamma)\backslash E(T)=P\cup N$  where P is the set of edges with positive weights and N is the set of remaining edges. Define a new weight function  $\tau$  on  $\Gamma$  by

$$au(e) = (\omega_{\Gamma}^{tot}(e^{-}), \omega_{\Gamma}^{tot}(e^{+})), \quad e \in E(T) \cup P,$$

and

$$au(e) = (\omega_\Gamma^{tot}(e^-), -\omega_\Gamma^{tot}(e^+)), \quad e \in N.$$

## Constructing 3-manifold GBS-group covers

Then  $(\Gamma, \tau)$  is a locally  $\pm$  weight constant GBS-graph, the total  $\pm$  weight cover of  $(\Gamma, \omega)$ . Thus  $\pi_1(\Gamma, \tau)$  is a 3-manifold group and we have a 3-manifold GBS-group cover

$$\varphi:\pi_1(\Gamma,\tau)\to\pi_1(\Gamma,\omega)$$

defined by the identity map on  $\Gamma$  and suitable pinches.

#### Final comments

- (i) The 3-manifold GBS-group covers constructed are *minimal* in the sense that all others factor through them.
- (ii) The kernels of the covering maps can be computed.